

Bắt đầu

Kết thúc

Motor quay

IN1 = HIGH

IN2 = LOW

Delay 2s

Delay 2s

Motor đảo chiều

IN1 = LOW

IN2 = HIGH

```
const int in1 = 5;
```

```
const int in2 = 4;
```

```
void loop() {
```

```
    digitalWrite(in1, HIGH);
```

```
    digitalWrite(in2, LOW);
```

```
digitalWrite(in1, LOW);  
digitalWrite(in2, HIGH);
```

```
delay(2000);
```

```
delay(2000);
```

```
}
```

```
void setup() {  
    pinMode(in1, OUTPUT);  
    pinMode(in2, OUTPUT);  
}
```